EKINOX-N



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SIMULATOR AND FAULT DETECTION SYSTEM

EKINOX-N is SW based system that generates standard and / or proprietary NMEA0183/2000 sentences through user configurable serial ports and / or Ethernet TCP, UDP connections.

- Generating complete Navigation systems data.
- Configurable serial port, communication speed, transmission and data frequency.
- Definition of Ethernet TCP/UDP definition for any system.
- Custom TalkerID.
- Custom HDLC data.
- Corrupt, missing data, and faulty unit isolation detection.
- NMEA Terminal screen data monitor
- Binary data TX and monitoring.
- TCP/UDP terminal for general use.
- Replay on the interactive map and data analysis.

It can generate sentences provided by various navigational devices that generate data according to the NMEA/ IEC61162 protocol and these sentences can be transmitted to one or more receivers. With the capability that the system will provide, testing easily its own systems and devices, and solving many problems that will be encountered in the field beforehand are possible. The system provides virtual creation and use of all devices used in navigation systems, monitoring data flow between devices, recording, replaying on the map.



EKINOX-N

SIMULATOR AND FAULT DETECTION SYSTEM

Creating sentences for any device, determining the sentences to	be created
Configurable serial port, communication speed, transmission and	data frequency
Definition of Ethernet TCP/UDP definition for any system	
Definition of live simulation for each device	
Custom TalkerID	
Custom HDLC data	
Data-Log	
Displaying the information coming with the analyzer and the inco	rrect information
Coordinated operation of all virtual devices	
NMEA terminal screen for general use	
Binary data TX/RX and display	
User-friendly interface	
Save and restore device settings config	
Broadcast and monocast over TCP or UDP	
General purpose TCP/UDP terminal	
High speed URI-10 interface unit	
Transmission up to 3Mbaud	
SAMPLE DEVICES WITH SIMULATION / ANALYSIS	
GPS(GLL,RMC,VTG,ZDA,GGA,GSA,GSV,XTE,RMB,DTM)	
Gyro (HDT,HDG,HDM,ROT,TSS1,HRP)	
Magnetic compass	
ECHO Sounder (DPT,DBT,DBK,DBS)	
EM Log (VHW,VLW,VBW)	
Anemometer (MWD,MWV,VWR,VWT,MTW)	
AIS (Class A, Class B vehicles)	
Radar (TLL,TTM,OSD)	